

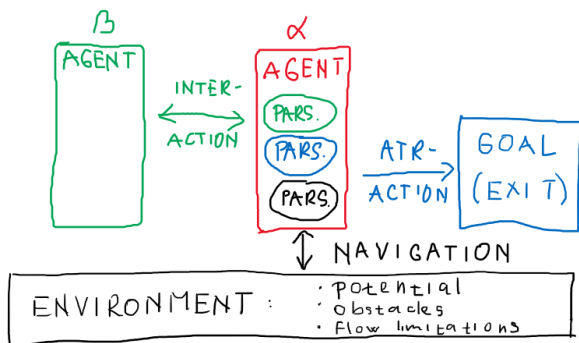
Heterogeneous Agents in Cellular Models of Pedestrian Flow

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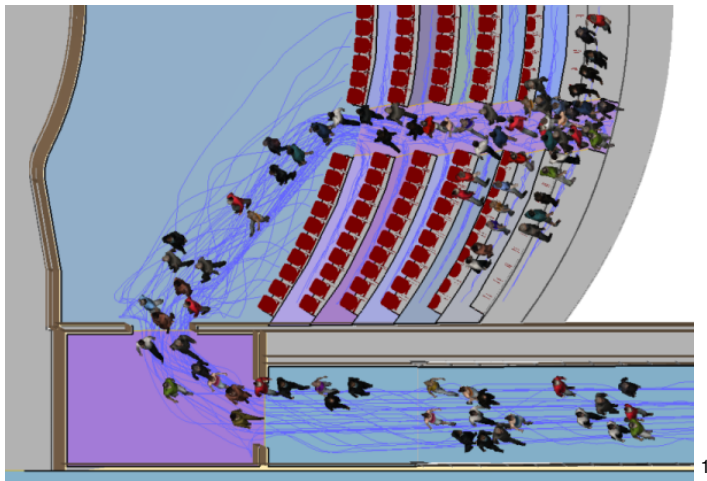
Scope of the talk

Evacuation model components



- Heterogeneity in parameters related to Navigation, Attraction, Interaction.
- Is the heterogeneity necessary?
- How to implement it?

Microscopic Agent-Based Models of Pedestrians



¹PathFinder, Thunderhead eng.

Social Force Model for Pedestrian Dynamics

Dirk Helbing and Péter Molnár. Phys. Rev. E 51 (1995)

Newtonian equations of motion

$$\ddot{\mathbf{x}}_{\alpha}(t) = \mathbf{F}_{\alpha}^{(\text{mot})} + \mathbf{F}_{\alpha}^{(\text{int})} + \mathbf{F}_{\alpha}^{(\text{env})} + \mathbf{F}_{\alpha}^{(\text{ext})}$$

- Attraction to the exit

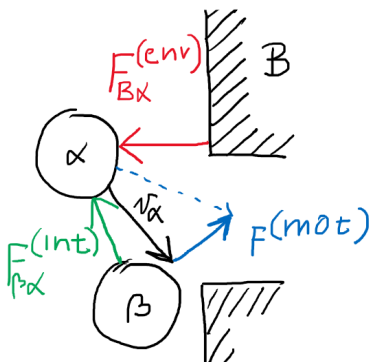
$$\mathbf{F}_{\alpha}^{(\text{mot})} \propto v_{\alpha}^0 \mathbf{e}_{\alpha} - \mathbf{v}_{\alpha}$$

- Repulsion from others

$$\mathbf{F}_{\alpha}^{(\text{int})} = \sum_{\beta \neq \alpha} \mathbf{F}_{\beta\alpha}^{(\text{int})}$$

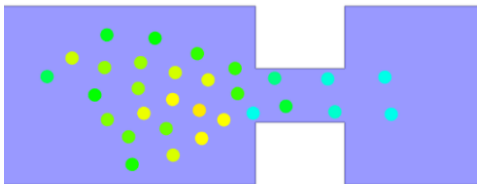
- Repulsion from obstacles

$$\mathbf{F}_{\alpha}^{(\text{env})} = \sum_B \mathbf{F}_{B\alpha}^{(\text{env})}$$



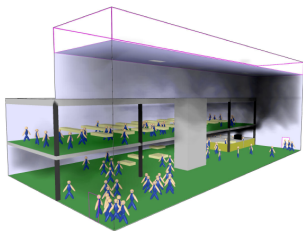
Implementation of Social Force Concept

JuPedSim – open-source simulator from JSC



- Generalized Centrifugal Force Model
- Collision-free Speed Model
- Collision avoidance left to the “Forces”

FDS+Evac – commercial evacuation software

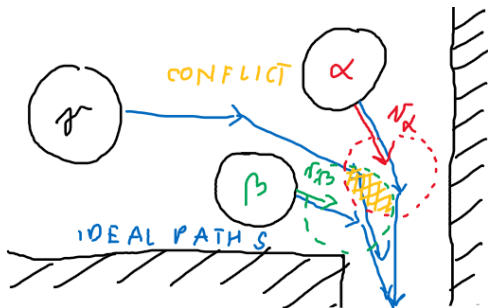


- Helbing Social-Force model
- Collision avoidance rules added
- Fire and human interaction

Path-Navigation and Floor-Field models

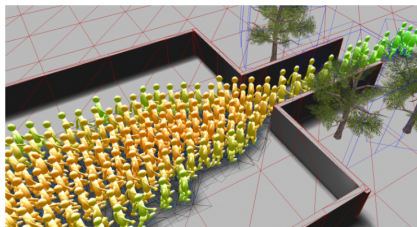
Navigation + Avoiding collisions + Solving conflicts

- Agent chooses direction along ideal path (navigation mesh, potential gradient).
- Agent adjusts its speed based on state of the neighbourhood (obstacles, density, other agents).
- Agents choosing to enter the same cell “negotiate”.



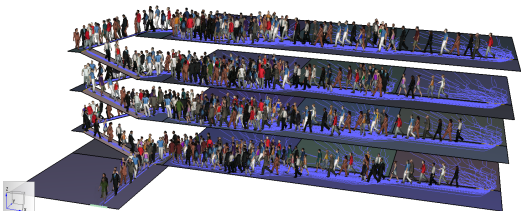
Implementation of Path-Navigation Models

VADERE – open-source simulator from Munich University of Applied Sciences



- Optimal Steps Model
- Behavioral Heuristics Model
- Navigation using floorfield potential

PathFinder – commercial evacuation software from Thunderhead eng.



- Path navigating concept
- Navigation mesh
- Collision avoidance + conflict solution algorithm

Cellular models

A. Kirchner and A. Schadschneider, Traffic and Granular Flow'01 (2002)

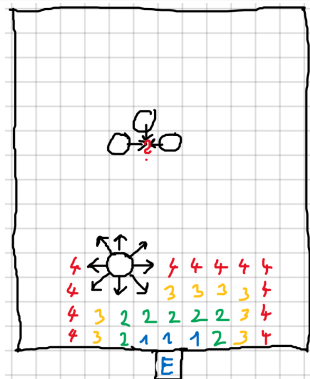
Floor-field cellular automata for pedestrian dynamics

$$P(x \rightarrow y | N) \propto \sum_F \exp\{k_F F_y\}$$

- Navigation to exit based on floor-field S

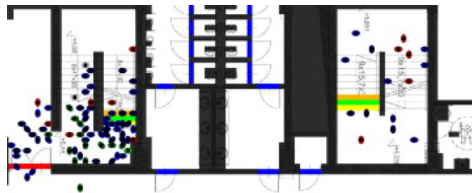
$$P(x \rightarrow y | N) \propto \exp\{-k_S S_y\}$$

- Conflict - more agents choosing the same target cell
- Hard-core repulsion or "longer interaction"
- Rule-based



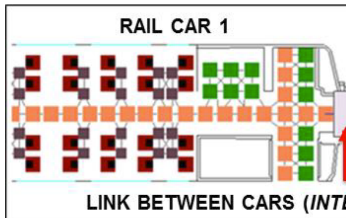
Implementation of Cellular models

Social Distance Model – academic model from AGH University, Kraków



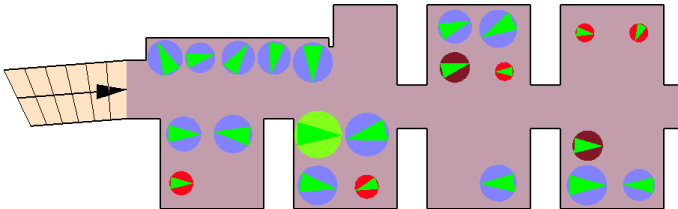
- Allianz Arena Munich, Wisla Krakow
- Finer lattice + Proxemics inspired repulsion

Exodus – commercial evacuation software from University of Greenwich



- BuildingExodus, TrainExodus, PlainExodus, ...
- Strictly rule based
- Waiting times and similar from measurements

Heterogeneity of Agents



Heterogeneity in Velocity and Size

Typical for space continuous models

Heterogeneity by variance of parameters

- Desired velocity

$$v_{\alpha}^0 \sim \mathcal{N}(\mu_v, \sigma_v^2)$$

- Agent radius/shape

$$R_{\alpha} \sim \mathcal{N}(\mu_R, \sigma_R^2)$$

- Acceleration parameters

$$a_{\alpha} \sim \mathcal{U}(a_{\min}, a_{\max})$$

Heterogeneity by introduction of different groups

- Adults, Children, Seniors
- Without or with limitations, or handicap

Velocity and size in cellular models

Size - finer grid

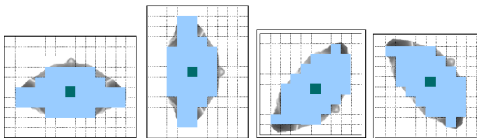
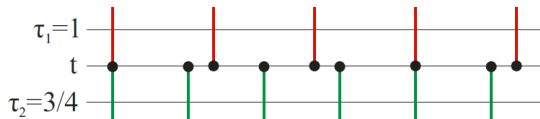


Figure 2: Sample pedestrian maps for different orientations

Velocity - asynchronous update



Different strategies for passing through the crowd

Hrabák, Bukáček and Krbálek. *Transportmetrica A* (2018)

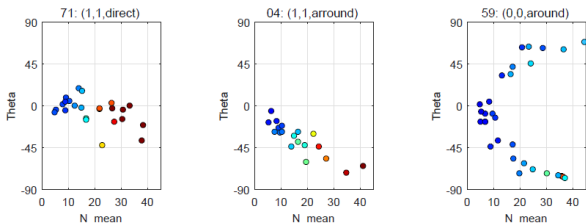
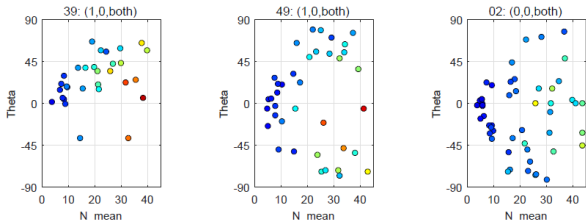
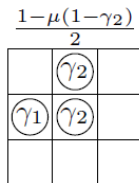
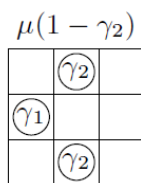
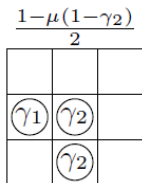
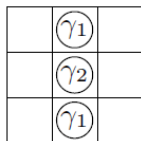
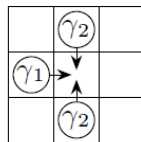
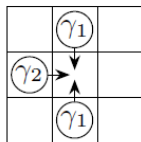


Figure 14. $\theta - \bar{N} - TT$ graphs for three representatives of studied strategies. Colormap reflects TT and is the same as in Figure 13



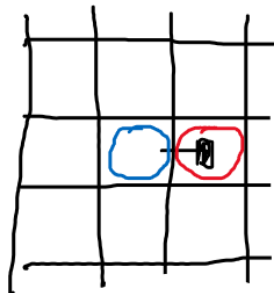
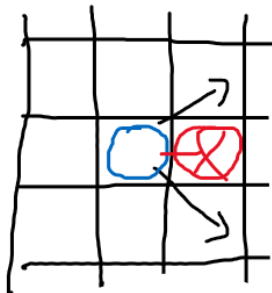
Agressiveness

A way of winning conflicts



Choice of the target cell

Two strategies



To be continued ...