

# Variational Inference for Blind Image Deconvolution

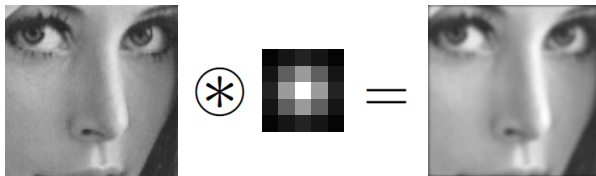
Antonie Brožová

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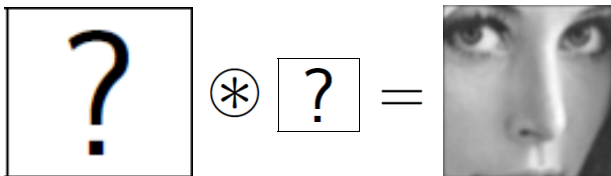
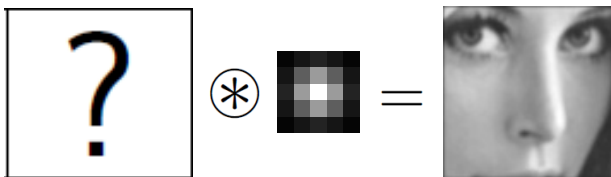
# Blurred image model

Blurred image is convolution of sharp image and point spread function (PSF) (assuming space-invariant PSF)

$$D = X \circledast K + n$$



# Blind image deconvolution



# Bayesian approach

Convolution in matrix form + gaussian noise

$$\mathbf{d} = \mathbf{X}\mathbf{k} + \mathbf{n}, \quad \mathbf{n} \sim \mathcal{N}(\mathbf{0}, \omega\mathbf{I}),$$

Priors must be well-chosen to avoid trivial solution

$$p(\mathbf{x}, \mathbf{k} | \mathbf{d}) \propto p(\mathbf{d} | \mathbf{x}, \mathbf{k})p(\mathbf{x}, \mathbf{k}),$$

# Variational Bayes

Approximation of posterior distribution

$$p(\boldsymbol{\theta}|\mathbf{d}) \sim q(\boldsymbol{\theta}|\mathbf{d}),$$

$$q(\boldsymbol{\theta}|\mathbf{d}) = \prod_i q(\theta_i|\mathbf{d})$$

$$q(\theta_i|\mathbf{d}) \propto \exp \left[ \mathbb{E}_{q(\boldsymbol{\theta}_{\setminus i}|\mathbf{d})} [\ln p(\boldsymbol{\theta}, \mathbf{d})] \right],$$

Kullback-Leibler divergence of  $q$  from  $p$

$$KL(q(\boldsymbol{\theta}|\mathbf{d}) \parallel p(\boldsymbol{\theta}|\mathbf{d})) = \mathbb{E}_{q(\boldsymbol{\theta}|\mathbf{d})} \left[ \ln \frac{q(\boldsymbol{\theta}|\mathbf{d})}{p(\boldsymbol{\theta}|\mathbf{d})} \right]$$

# IVB algorithm

- Conjugate distributions lead to a system of linear equations
- Iteratively minimizes Kullback-Leibler divergence
- Fast, but requires system of linear equations

# ELBO - Evidence Lower Bound

$$\begin{aligned}KL(q(\boldsymbol{\theta}|\mathbf{d}) \parallel p(\boldsymbol{\theta}|\mathbf{d})) &= \mathbb{E}_{q(\boldsymbol{\theta}|\mathbf{d})} \left[ \ln \frac{q(\boldsymbol{\theta}|\mathbf{d})}{p(\boldsymbol{\theta}, \mathbf{d})} \right] + p(\mathbf{d}) = \\ &= -\mathcal{L} + p(\mathbf{d}) \\ \mathcal{L} &= p(\mathbf{d}) - KL(q(\boldsymbol{\theta}|\mathbf{d}) \parallel p(\boldsymbol{\theta}|\mathbf{d}))\end{aligned}$$

- Max ELBO = Min KL
- Gradient descent - slow, but system of linear equations is not needed

# Reparametrization trick

- $\mathcal{L}$  requires gradients of expected values with respect to  $q(\boldsymbol{\theta}|\mathbf{d})$  to be known
- If  $q(\theta|d) \sim \mathcal{N}(\mu, \sigma^2)$ , then  $\theta$  can be reparametrized as  $\theta = \sigma\epsilon + \mu, \epsilon \sim \mathcal{N}(0, 1)$
- $\nabla_{\mu} \mathbb{E}_{q(\theta|d)} [f(\theta, d)] \approx \frac{1}{L} \sum_{l=1}^L \nabla_{\mu} (f(\sigma\epsilon^{(l)} + \mu, d))$



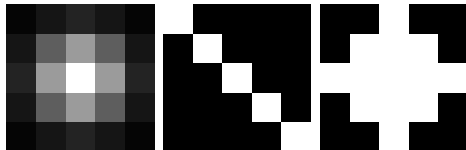
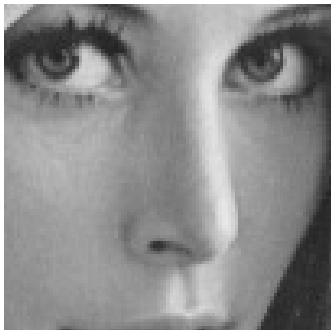
# Vadam

- Vadam - Variational Adam optimiser proposed by Khan et al. (2018)
- Derived for distributions from exponential family to maximize ELBO
- The update of posterior parameters is derived from update of natural parameters
- Computes gradient in sample drawn from posterior distribution - the gradient descent is stochastic

# Comparison of two algorithms

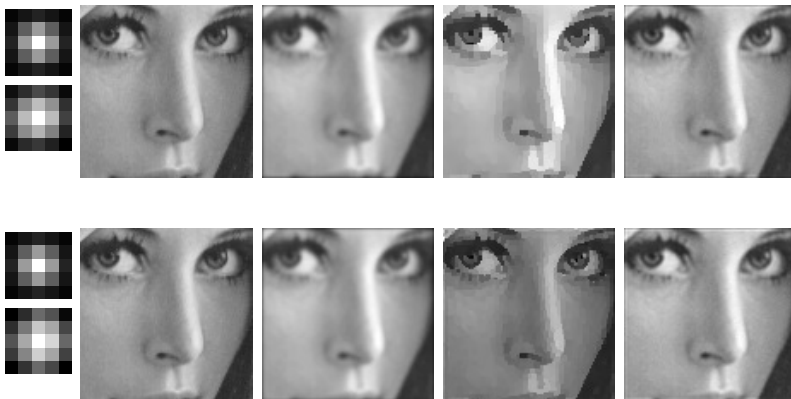
- 1 Only IVB steps
- 2 IVB steps for all parameters except for mean and covariance of PSF  $\mu_k$  a  $\Sigma_k$ , which are estimated using gradient descent

# Sharp Image and PSF



- Posterior distribution  $p(\mathbf{k}|\mathbf{d}) = \mathcal{N}(\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$
- Image is assumed to be piece-wise constant

# IVB and ELBO for diagonal covariance matrix



# IVB and ELBO for full covariance matrix



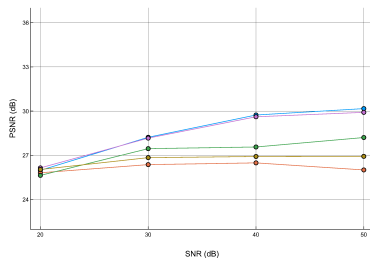
## Higher number of samples for reparametrization trick

- The algorithm takes only one sample of  $\epsilon$  to estimate  $\mu_k$  a  $\Sigma_k$
- One sample is enough only in the case of diagonal covariance matrix
- Taking 25 samples gives better results, but the reconstruction still isn't as accurate as in the case of full covariance matrix in IVB algorithm
- Higher number of sample would increase accuracy of reconstruction, but it is too costly

# Vadam

- Covariance matrix can be approximated using gradient with respect to mean in case of normally distributed random variable
- Reaches the same accuracy as IVB algorithm with full covariance matrix, even though it uses only diagonal one

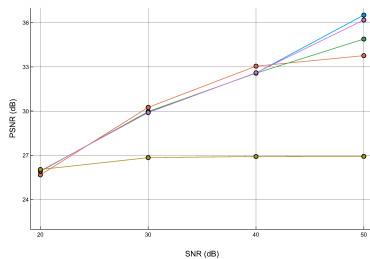
# PSNR of the mean of image posterior



**Figure:** Blue line shows results of IVB alg. with full covariance, red line of IVB alg. with diagonal covariance, green line of ELBO with diagonal covariance, purple of ELBO with Vadam and brown PSNR of blurred image.



# PSNR of non-blind reconstruction



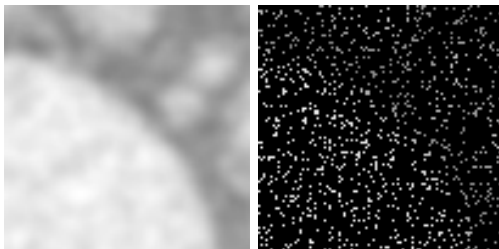
**Figure:** Blue line shows results of IVB alg. with full covariance, red line of IVB alg. with diagonal covariance, green line of ELBO with diagonal covariance, purple of ELBO with Vadam and brown PSNR of blurred image.

# Conclusion

- Steps of IVB algorithm can be replaced by maximization of ELBO using Vadam optimiser without loss of accuracy, which is more flexible than IVB algorithm

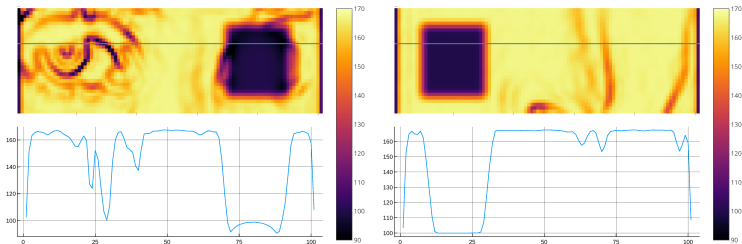
# Incomplete image

- Pixels are scanned one by one in environmental scanning microscopy
- Scientists usually aren't interested in the whole image, only in a certain area
- Presented algorithms estimate not only images and PSFs, but also variance in the image

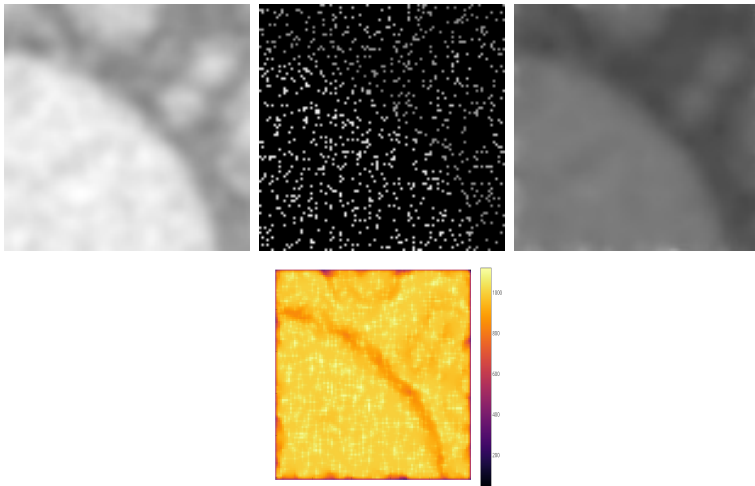


# Posterior precision in missing areas

- Two areas in image were deleted - one with high variance and one with almost constant values
- Lower figure shows values of posterior precision in pixels marked with blue line in image above



# Precision estimate on image from electron scanning microscope



# Conclusion

- Estimation of parameters with ELBO and Vadam shows the same accuracy as estimate with no stochasticity
- The algorithm has potential to find more interesting areas in image
- Future work: analyse the algorithm on larger images with more realistic blurs

## References:

- Microscope image from Ing. Vilém Neděla, Ph.D. from Institute of Scientific Instruments CAS in Brno.
- Lena [online]. Available from: <https://www.cosy.sbg.ac.at/~pmeerw/Watermarking/lena.html>, cited 2020-10-12.
- KINGMA, D. a M. WELLING, Auto-Encoding Variational Bayes. ArXiv:1312.6114v10 [stat.ML], 2014.
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