



Application of Neural Networks for Acoustic Emission Method

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AI for AE

- Acoustic emission (AE)
- BP (feed-forward) networks for location of AE sources
- Identification of helicopter gear box modes
- Detection of plastic deformation in materials
- Detection of AE bursts (material cracking) in noisy continuous signals
- Challenges for the future





ACOUSTIC EMISSION (AE) METHOD

Passive monitoring of ultrasonic elastic waves initiated by various processes in materials.

- Burst AE: plastic deformation of metals, crack growth, friction, material failure...
- **Continuous AE:** leakage of liquids under pressure, machining, welding, monitoring of technological processes and devices...





MACHINE LEARNING APPLICATIONS



Multilayer Back-propagation networks

Localization of material defects (especially for cases of complex structures)

Convolutional neural networks (CNN)

Condition monitoring of rotating mechanisms *(bearings, gearboxes, etc.)*





Backpropagation (feed-forward) networks





C2

unexpected fatal crack

Long-term fatigue tests of riveted aircraft wing flange









REMOTE AE MONITORING









Demonstration scheme of AE signal measurement (2D model)

- configuration of AE sensors S₁-S₄ placed on planar body



tested area





Definition of arrival time profile (ATP)

- signal arrival time treatment is inspired by the analysis of signal detection chronology



Independence of ATP on wave velocity and scale changes

Only the AE signal arrival times t_i are available. Assuming t_s as the time of AE source initiation, it is easy to revise the original formula, while $T_i = t_i - t_s$





Training of neural network

- network architecture (approximate numbers of neurons in each layer): **N-35-25-2**
- initial weights were adjusted by *statistical optimization* of starting neuron potentials
- weights and biases were adjusted by fast *resilient back-propagation* algorithm with *momentum* and *regularization* (training data set of virtual AE sources)







APPROXIMATION FEATURES OF ANN

Spreading of virtual training sources and their projection by learned neural network







used sensors: 1 3 6 7 9





LOCATION OF REAL AE SOURCES

Results for two different configuration of sensors













Convolutional networks





Renewed helicopter gear box running-up







High-frequency-density spectrogram







Signals from emission channels - "idling" mode







Signals from emission channels - "engine starting" mode







Signals from emission channels - "L nominal, R 80%" mode





Tensile tests

Training and validation data selection for Exp. A and B



Experimental setup



23.6. - 27.6.2022

G

-G

®

Application of *Inception Time* architecture











AUDIO demo of AE signal







AUDIO demo of AE signal





Initiation of Crack - an overview (source: ScienceDirect)



100 µm

-Surface

(b)











AE SIGNAL DEMO BLOCK



DEMONSTRATION OF TYPICAL AE EVENT LIST ESTIMATION BY ANN







Estimation of **drill bit sharpness**



Experimental setup

Specimen and AE sensors

Drill bit dulling

(audio demos...)





NEW drill bit "sound"





NEW drill bit "sound"





Drill bit "sound" after 5th dulling



AI model?







Thank you for your attention...