Estimating Sparse Parameterization of Neural Networks

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Pruning

Motivation

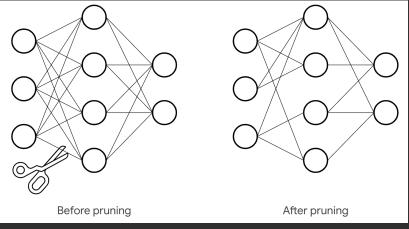


Figure 1: Example of pruning. Taken from: https://blog.tensorflow.org/2019/05 tf-model-optimization-toolkit-pruning-API.html.

Problem Formulation

- Sparse parameterization increases interpretability and reduces model complexity while preserving overall information (*pruning*).
- Probabilistic approach.
- A new approach to optimization using natural parameter distributions
 a follow-up to Mohammad Khan's paper Fast and Scalable Bayesian Deep Learning by Weight-Perturbation in Adam.
- The goal: build methods that learn an arbitrarily complex model and find a sparse parameterization.
- Julia 1.6.xx, Flux.jl ML library.



Why is it Good to be Bayesian?

Bayes' theorem

$$p(\boldsymbol{\theta}|\mathcal{D}) = \frac{p(\mathcal{D}|\boldsymbol{\theta})p(\boldsymbol{\theta})}{p(\mathcal{D})} = \frac{p(\mathcal{D}|\boldsymbol{\theta})p(\boldsymbol{\theta})}{\int p(\mathcal{D},\boldsymbol{\theta})d\boldsymbol{\theta}}$$

$$lacksymbol{ heta} p(\mathcal{D}|oldsymbol{ heta})$$
 - likelihood

p
$$(oldsymbol{ heta}|\mathcal{D})$$
 - posterior

$$lacksquare$$
 $p(oldsymbol{ heta})$ - prior

$$\blacksquare p(\mathcal{D})$$
 - evidence



(1)

Neural Networks

Artificial NN vs. Bayesian NN

$$\mathbf{h}^{(0)} = \mathbf{X}, \ \mathbf{h}^{(l)} = a \left(\mathbf{W}^{(l)} \mathbf{h}^{(l-1)} + \mathbf{b}^{(l)} \right), \ l = 1, \dots, L$$
$$\mathbf{y} = a^{(\text{out})} \left(\mathbf{W}^{(L+1)} \mathbf{h}^{(L)} \right)$$
(2)

ANN

Likelihood, $(L_1 \text{ regularization})$

Goal: $\mathbf{y} = f(\mathbf{X}, \boldsymbol{\theta})$ deterministic function

BNN

$$oldsymbol{\mathcal{D}} = (\mathbf{y}, \mathbf{X})$$
, $oldsymbol{ heta} = \{\mathbf{W}^{(l)}, \mathbf{b}^{(l)}\}_{l=1}^{L+1}$

Likelihood & prior

Goal:
$$\underbrace{\mathbf{y} = f(\mathbf{X}, \boldsymbol{\theta})}_{\text{random function}}, p(\boldsymbol{\theta}|\mathcal{D})$$



Shrinkage Priors

- Model parameters (*weights, biases*) (mostly) in combination with model hyper-parameters $\alpha \rightarrow$ hierarchical parameterization.
- Gaussian Scale Mixtures as marginal model parameters prior:

$$p(\boldsymbol{\theta}) = \int \mathcal{N}(\boldsymbol{0}, \boldsymbol{\alpha}^2 \boldsymbol{\sigma}^2) p(\boldsymbol{\alpha}) d\boldsymbol{\alpha}$$
(3)

	Variance prior $p(lpha)$	p_j^2 Marginal prior $p(\theta_j)$	
	Exponential	Laplace	
	Inverse-Gamma	Student-t	
	Bernoulli	Spike and Slab	
able	1: Variance priors and	their corresponding marginal p	riors



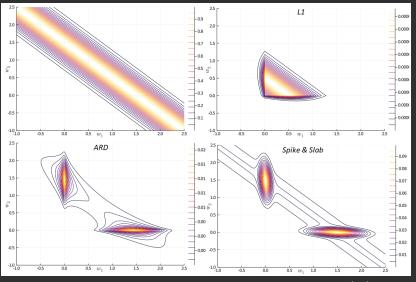


Figure 2: Gaussian likelihood with no prior vs. with Laplace (L1), Student-t (ARD) and Spike and Slab prior. Taken from: [1].



Variational Inference

Problem: (mostly) intractable integrals ∫ p(D, z)dz in Bayes' rule.
 Solution: find surrogate distribution q(z) ≈ p(z|D).

Evidence Lower Bound (ELBO) & KL Divergence

$$\log p(\mathcal{D}) = \mathcal{L}(q(\mathbf{z})) + \mathsf{KL}(q(\mathbf{z})||p(\mathbf{z}|\mathcal{D}))$$
(4)

Maximizing the ELBO

$$q_{\mathsf{opt}}(\mathbf{z}) = \underset{q(\mathbf{z})\in\mathcal{Q}}{\arg\max} \mathcal{L}(q(\mathbf{z}))$$
(5)



Optimization

Standard vs. Variational Optimization

Standard way

Laplace prior as the L₁ regularization:

$$\operatorname{argmax}_{\boldsymbol{ heta}} \log p(\mathcal{D}|\boldsymbol{ heta}) + \lambda \sum_{j=1}^{J} |\theta_j|$$
 (6)

Variational way

- **Factorize the** posterior $q(\mathbf{z}) \approx q(\boldsymbol{\theta}) \overline{q(\boldsymbol{\psi})}$.
- Analytical solution of the ELBO for the factor $q(\psi|\gamma, \delta)$.
- Factor $q(\boldsymbol{\theta})$ meets the VADAM conditions.



Variational ADAM with the ARD Prior

We propose

$$f_{\text{obj}} = -\frac{1}{N} \sum_{n=1}^{N} \log p(\mathcal{D}_n | \boldsymbol{\theta}) - \sum_{j=1}^{J} \frac{1}{2} \theta_j^2 \psi_j$$

- 1. Initialize prior parameters, learning rates in ADAM.
- 2. Calculate posterior parameters of Gamma factor $\gamma_{j,(t)}$, $\delta_{j,(t)}$.
- **3**. $\psi_{j,(t)} \leftarrow \frac{\gamma_{j,(t)}}{\delta_{j,(t)}}$.
- 4. **Update** f_{obj} with VADAM.
- 5. Update $\gamma_{j,(t)}$, $\delta_{j,(t)}$
- **6**. $(t+1) \leftarrow (t)$.



(7)

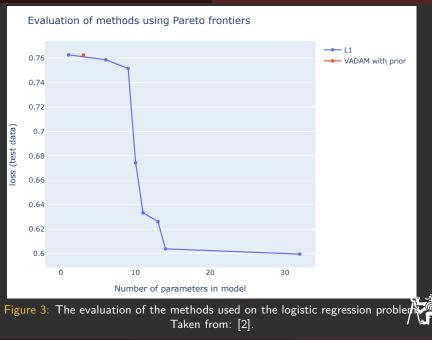
Sparse Logistic Regression

- **Dataset**: IRIS¹, $\mathcal{D} = (\mathbf{y}, \mathbf{X})$, where
 - $\mathbf{y} \in \{\text{setosa}, \text{versicolor}, \text{virginica}\}^{150}, \mathbf{X} \in \mathbb{R}^{150 \times 4}.$
- Model architecture: input layer of dimension 4, one hidden layer containing 8 neurons and ReLU activation, output layer of dimension 3 with softmax output activation → 67 trainable parameters.
- Goal: prune the network and obtain a sparse parameterization with minimal error increase on test data.
- Methods: L₁ regularization & Variational ADAM with the ARD prior.



¹https://archive.ics.uci.edu/ml/datasets/iris

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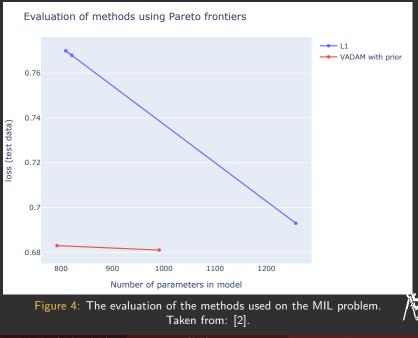
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Sparse Multi-Instance Learning

- **Dataset**: Musk² with 92 *bags* containing 476 instances each of dimension 166 and $\mathbf{y} \in \{0, 1\}^{92}$.
- Model architecture: input layer of dimension 166, first hidden layer containing 10 neurons and tanh activation, pooling layer with MeanMax aggregation, second hidden layer containing 10 neurons and tanh activation, output layer of dimension 2 with sigmoid output activation → 1922 trainable parameters.
- Goal: prune the network and obtain a sparse parameterization with minimal error increase on test data.
- Methods: L₁ regularization & Variational ADAM with the ARD prior.



²https://archive.ics.uci.edu/ml/datasets/Musk+(Version+2)



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Conclusion

- A new method was proposed to find a sparse parameterization of neural networks.
- Method was applied to a logistic regression model and a multi-instance learning model.
- Subsequently, it was tested and compared with the classical method of regularization in neural networks.



Thank you for your attention.



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References

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- 2 KULIČKA L. Estimating Sparse Parameterization of Neural Networks. Master's Thesis. Czech Technical University in Prague. 2022.

