

Parameter Estimation in Cyclic Plastic Loading

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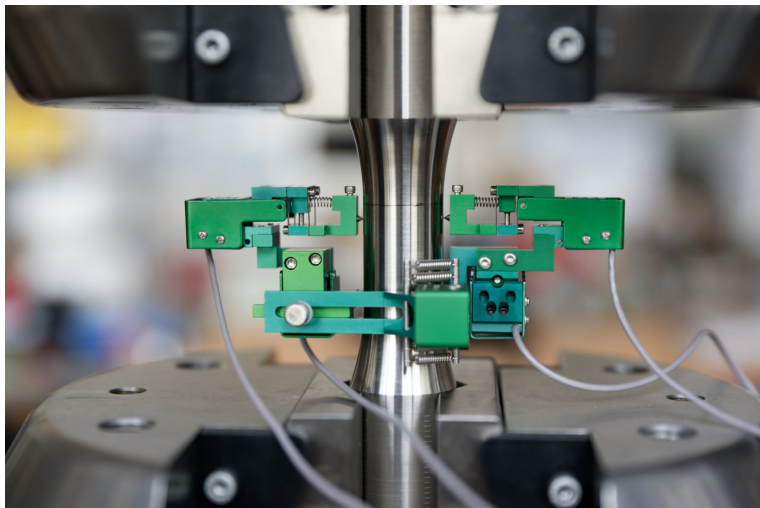
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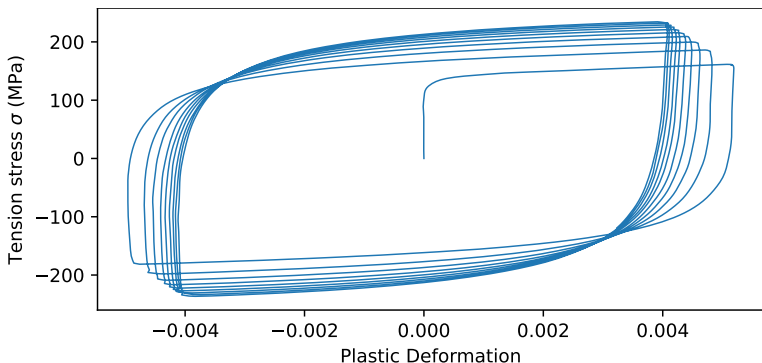
Cyclic Loading Measurement



The axial-torsional extensometer Epsilon Tech 3550.

Cyclic Loading and the Bauschinger Effect

- Bauschinger effect
- Permanent changes in the metallic specimen under cyclic loading



Denoised measured data from cyclic plastic loading.

Hardening Model MAFTr

- Developed by Marek et al. in 2022 ¹
- Needs to be calibrated on cyclic loading experimental data.

Parameter	Unit	Description
k_0	MPa	Initial yield strength
κ_1	MPa	Adjustment of the rate of isotropic hardening
κ_2	MPa ⁻¹	Inverted asymptotic limit of isotropic hardening
c_i	-	Adjustment of the evolution rates of the backstress components
a_i	MPa	Asymptotic limits of the backstress components

Parameters of analytical model developed by Marek et al.

¹R. Marek et al. "A quick calibration tool for cyclic plasticity using analytical solution". In: Engineering Mechanics 27/28 (May 2022), pp. 249 –252. DOI: 10.21495/512249.

Synthetic datasets for Plastic Deformation

- \mathbf{D}_1 dataset
 - consists of pairs $(\boldsymbol{\theta}_i, S(\boldsymbol{\theta}_i))$, where $\boldsymbol{\theta}_i$ is generated from the a priori distribution.
 - Plastic deformation setup ϵ_p remains constant across the dataset.
 - Dataset length is $L = 10^6$.
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- Extended \mathbf{D}_2 Dataset
 - consists of triplets $(\boldsymbol{\theta}_i, S(\boldsymbol{\theta}_i), \epsilon_p)$.
 - Dataset length is $L = 10^6$.

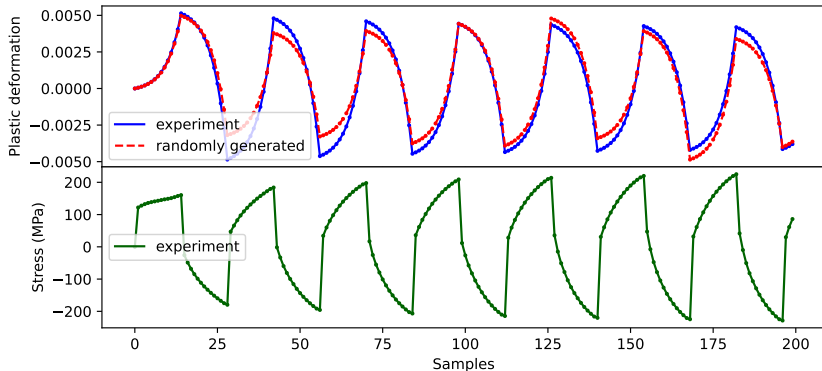
A Priori Distribution for parameters

- A uniform distribution is selected for all 11 parameters.
- Conditions:
 - Sum of a_i parameters in the range of [150, 350].
 - Ordering of c_i parameters to ensure uniqueness of the training objective.

	k_0	κ_1	κ_2^{-1}	$\log(c_1)$	$\log(c_{2,3,4})$	$a_{1,2,3,4}$
min	15	100	30	$\log(1000)$	$\log(50)$	0
max	250	10000	150	$\log(10000)$	$\log(2000)$	350

Range of the a priori uniform distribution for each parameter.

Data Downsampling Strategy



Top: Interpolated plastic deformation covering each load segment by 15 points.

Bottom: Interpolated stress from the measured data.

Approaches

- Neural Networks
 - Feed Forward Networks
 - LSTM ¹
 - GRU ²
- Non-neural methods
 - TTOpt ³
- Refinement using the Nelder-Mead method

¹Sepp Hochreiter and Jürgen Schmidhuber. “Long Short-term Memory”. In: Neural computation 9 (Dec. 1997), pp. 1735–80. DOI: 10.1162/neco.1997.9.8.1735.

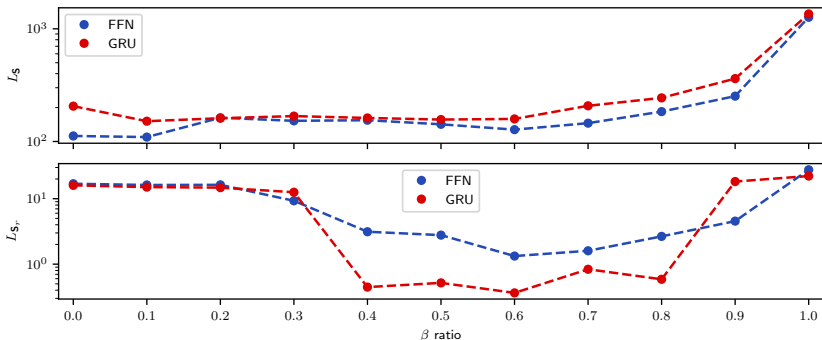
²Kyunghyun Cho et al. Learning Phrase Representations using RNN Encoder-Decoder for Statistical Machine Translation. 2014. arXiv: 1406.1078 [cs.CL].

³Konstantin Sozykin et al. TTOpt: A Maximum Volume Quantized Tensor Train-based Optimization and its Application to Reinforcement Learning. arXiv:2205.00293 [cs, math].

Novel loss function

- Calculating $\widehat{\mathbf{S}} := M_{\widehat{\boldsymbol{\theta}}}(\epsilon_p)$ from NN-predicted $\widehat{\boldsymbol{\theta}}$, where $M_{\boldsymbol{\theta}}$ represents the MAFTr model.

$$L(\widehat{\boldsymbol{\theta}}_{\mathcal{N}}, \boldsymbol{\theta}_{\mathcal{N}}, \widehat{\mathbf{S}}, \mathbf{S}) := k \|\widehat{\boldsymbol{\theta}} - \boldsymbol{\theta}\|_2^2 + \alpha(1-k) \|\widehat{\mathbf{S}} - \mathbf{S}\|_2^2, \quad k \in [0, 1], \quad \alpha \in \mathbb{R}_+.$$



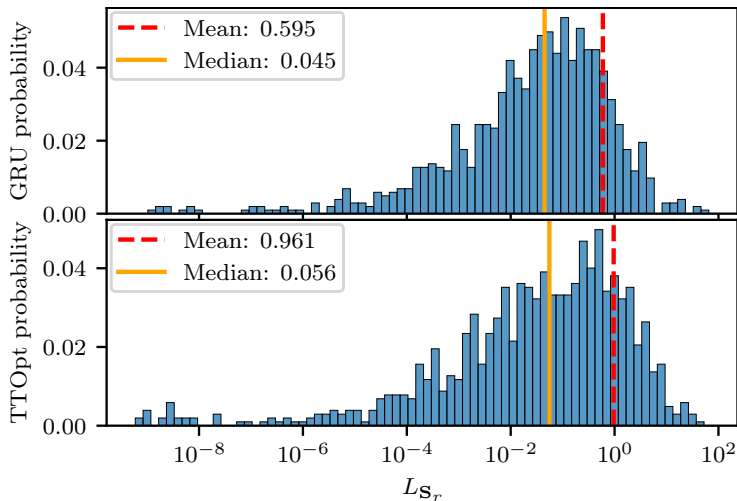
Comparison of L_{θ} and L_S metrics for FFN and GRU trained with $L(\widehat{\boldsymbol{\theta}}_{\mathcal{N}}, \boldsymbol{\theta}_{\mathcal{N}}, \widehat{\mathbf{S}}, \mathbf{S})$ for different k values.

Numerical results on synthetic data

architecture	dataset	L_S	$L_S^{(r)}$
GRU	D_1^T	111.64	0.137
LSTM	D_1^T	149.91	0.510
FFN	D_1^T	106.90	2.314
GRU	D_2^T	242.43	0.595
LSTM	D_2^T	528.03	7.523
FFN	D_2^T	350.02	7.058
TTOpt	D_2^T	63.30	0.961

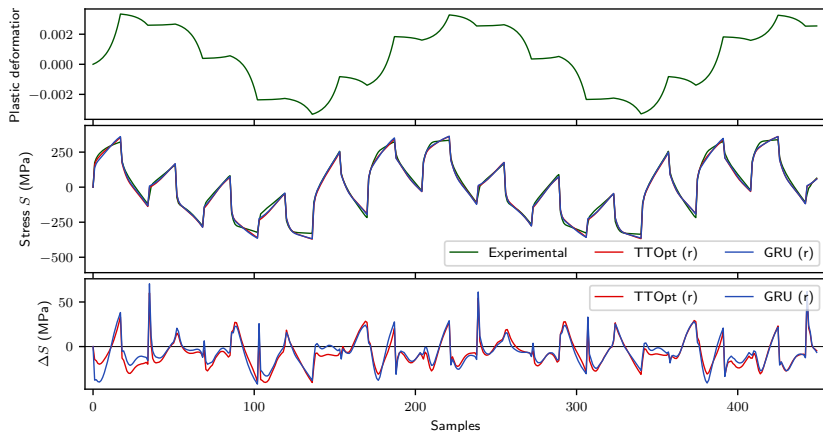
Metrics and their refined values of selected GRU and FFN networks compared to TTOpt on test datasets D_1^T and D_2^T .

Prediction analysis



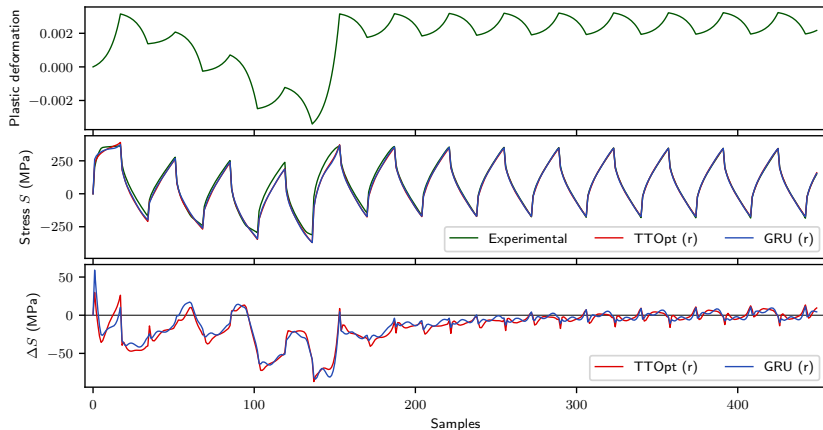
Histogram of refined predictions of both GRU and TTOpt on test dataset D^T .

Validation 1



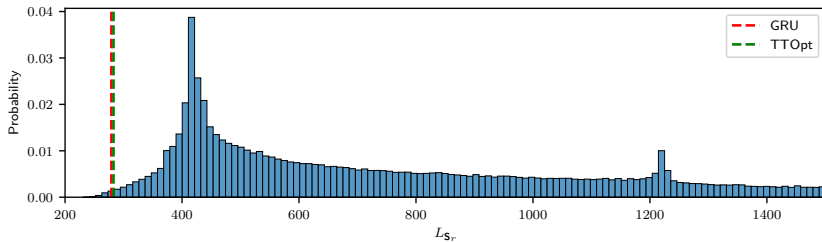
Top: Plastic deformation in the measured experiment #1. Middle: Predicted stress using the refined estimated parameters θ of both GRU and TTOpt. Bottom: Stress prediction error.

Validation 2



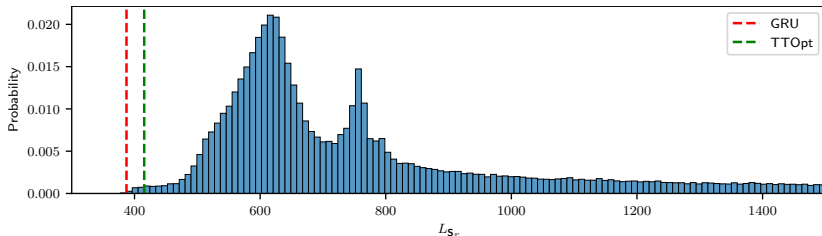
Top: Plastic deformation in the measured experiment #2. Middle: Predicted stress using the refined estimated parameters θ of both GRU and TTOpt. Bottom: Stress prediction error.

Validation 1 - Nelder Mead



Histogram of randomly generated θ using the a priori distribution after its refinement using the Nelder-Mead simplex optimization on experiment #1. For comparison, the refined predictions of GRU and TTOpt are depicted by dashed lines.

Validation 2 - Nelder Mead



Histogram of randomly generated θ using the a priori distribution after its refinement using the Nelder-Mead simplex optimization on experiment #2. For comparison, the refined predictions of GRU and TTOpt are depicted by dashed lines.

Conclusion

- The novel loss function combining L_θ and L_S enhances the training effectiveness.
- FFNs and CNNs appeared to be unstable on \mathbf{D}_2 dataset.
- Both GRU and TTOpt exhibit comparable performance on both synthetic and real-world data.
- The entire approach is not model specific and can be easily used with other material models.

Bibliography

- [1] R. Marek et al. "A quick calibration tool for cyclic plasticity using analytical solution". In: *Engineering Mechanics* 27/28 (May 2022), pp. 249–252. DOI: 10.21495/512249.
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- [6] John A. Nelder and Roger Mead. "A simplex method for function minimization". In: *Computer Journal* 7 (1965), pp. 308–313.

Data Downsampling Strategy

- Stress response recorded at 10Hz for 4 hours.
- Needs to preserve points of reversals.
- Each segment is downsampled to 15 points.

$$\epsilon_i^{(j)} := \epsilon_{i-1}^{(r)} + \sum_{k=1}^j \delta_k, \quad \forall i \in \{1, \dots, K\}, \quad \forall j \in \{1, \dots, N-1\},$$

- The increments follow a geometrical sequence:
$$\delta_{k+1} = \sqrt[N-1]{R} \delta_k, \quad \forall k \in \{1, \dots, N-1\}, \quad R = 20.$$