

# Numerical methods: Runge-Kutta methods and the Simpson's rule

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- Some problems can not be solved analytically
  - ▶ Interpolation and extrapolation
  - ▶ Ordinary or partial differential equations
  - ▶ Integration
- One needs an appropriate numerical method to approximate the solution to the problem
- Example - Balitsky-Kovchegov evolution equation:

$$\frac{\partial N(r, Y)}{\partial Y} = \int d\vec{r}_1 K(\vec{r}, \vec{r}_1, \vec{r}_2) (N(r_1, Y) + N(r_2, Y) - N(r, Y) - N(r_1, Y)N(r_2, Y)). \quad (1)$$

$$N(r, Y = 0) = 1 - \exp(-Ar^2) \quad (2)$$

## Simpson's rule

- Integration over the closed interval  $[a, b]$  spaced uniformly

$$x_i = a + ih, \quad i = 0, \dots, n, \quad h = \frac{b - a}{n}$$

- Special case of *Newton-Cotes integration formulas*
- Replace the integrated function by an interpolating polynomial of order  $n > 0$

$$\int_a^b f(x) dx \approx \int_a^b P_n(x) dx. \quad (3)$$

- Using Lagrange interpolation and integrating the interpolating polynomial:

$$\int_a^b P_n(x) dx = \sum_{i=0}^n f_i \int_a^b L_i(x) dx = h \sum_{i=0}^n f_i \int_0^n \phi_i(t) dt = h \sum_{i=0}^n f_i \alpha_i.$$

$$f_i = f(x_i) = f(a + ih) = P_n(x_i)$$

## Simpson's rule

- For  $n = 2$  (quadratic interpolation) we obtain the Simpson's 1/3 rule

$$\int_a^b f(x)dx \approx \int_a^b P_2(x)dx = h \left[ \frac{1}{3}f_0 + \frac{4}{3}f_1 + \frac{1}{3}f_2 \right] \quad (4)$$

- The above formula is applied directly to the entire interval  $[a, b]$
- **Composite rule**
  - ▶ Integrating function is not smooth over the entire interval  $[a, b]$
  - ▶ The interval  $[a, b]$  is equidistantly divided into the set of  $N$  subintervals
  - ▶ The formula is applied in each of the subintervals
  - ▶ Total approximate value of the integral is given as a sum of the approximations in each of subintervals

$$\int_a^b f(x)dx \approx \frac{h}{3} \left[ f(a) + 2 \sum_{i=1}^{\frac{N}{2}-1} f(x_{2i}) + 4 \sum_{i=1}^{\frac{N}{2}} f(x_{2i-1}) + f(b) \right]. \quad (5)$$

- ▶  $N$  has to be an even number!

## Application of the Simpson's rule

- Example of the code:

```
//simpson method for definite integrals
double simpson(double y[], int length, int n, double step){
    double sum = 0.;
    double Int;
    for(int i=1; i<n; i+=2){
        sum = sum+4.0*y[i];
    }
    for(int i=2; i<n-1; i+=2){
        sum = sum+2.0*y[i];
    }
    Int = step*(y[0]+y[n]+sum)/3.;
    return Int;
}
```

- Basic example provided in the attached file

- Approximation of the solution to the **Cauchy problem**

- ▶ Differential equation of the 1<sup>st</sup> order with an initial condition

$$y'(x) = f(x, y(x)), \quad y(x_0) = y_0. \quad (6)$$

- Let  $\eta_n$  be the approximation at point  $x_n$  of the exact solution  $y(x_n)$
- The approximation at point  $x_{n+1}$  is in general given as

$$\eta_{n+1} = \eta_n + h\Phi(x_n, \eta_n, h; f) \quad (7)$$

- ▶  $\Phi(x_n, \eta_n, h; f)$  is the increment function and  $h$  is the step size

$$\Phi(x_n, \eta_n, h; f) = \sum_{i=1}^s b_i K_i, \quad K_i = f \left( x_n + c_i h, \eta_n + h \sum_{j=1}^s a_{ij} K_j \right). \quad (8)$$

- Single-point approximation methods
- Explicit method -  $\eta_{n+1}$  depends only on  $\eta_n$

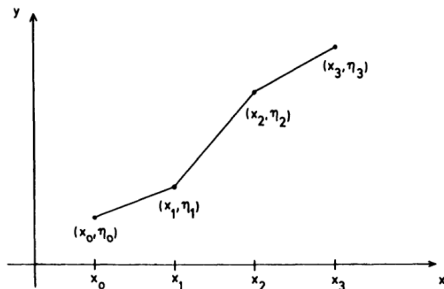
## Forward Euler method

- RK method of the first order
- $f(x, y(x))$  in (6) is the slope of  $y(x) \rightarrow$  for  $h \neq 0$

$$y(x+h) = y(x) + hf(x, y(x)). \quad (9)$$

- In the limit of  $h \rightarrow 0$  the approximation to (6) at point  $x_{n+1}$  is given as

$$\eta_{n+1} = \eta_n + hf(x_n, \eta_n), \quad x_{n+1} = x_n + h. \quad (10)$$



## Heun's method

- One of the two RK methods of the second order
- For  $s = 2$  in (8) the approximation of the exact solution  $y_n$  at  $(n + 1)$ -th step is

$$\eta_{n+1} = y_n + h\Phi(x_n, y_n, h; f) = y_n + h(b_1K_1 + b_2K_2)$$

using the expansion to the 2<sup>nd</sup> order of the Taylor series:

$$\eta_{n+1} = y_n + hf_n(b_1 + b_2) + h^2b_2c_2(f_{n,x} + f_n f_{n,y}) + \mathcal{O}(h^3)$$

- Compare it to the same expansion of the exact solution

$$y_{n+1} = y_n + hy'_n + \frac{h^2}{2}y''_n + \mathcal{O}(h^3) = y_n + hf_n + \frac{h^2}{2}(f_{n,x} + f_n f_{n,y}) + \mathcal{O}(h^3)$$

- The resulting coefficients are

$$b_1 + b_2 = 1 \quad \text{and} \quad b_2c_2 = \frac{1}{2} \rightarrow b_1 = \frac{1}{2}, \quad b_2 = \frac{1}{2} \quad \text{and} \quad c_2 = 1$$

- The resulting approximation prescription:

$$\eta_{n+1} = \eta_n + \frac{h}{2} [f(x_n, \eta_n) + f(x_n + h, \eta_n + hf(x_n, \eta_n))]. \quad (11)$$



- RK method of the fourth order
- Analogical approach to its derivation as in Heun's method
  - ▶ Fourth order of the Taylor's expansion applied to the approximation and exact solution
  - ▶ The increment function is given as

$$\Phi(x_n, \eta_n, h; f) = \frac{1}{6}(K_1 + 2K_2 + 2K_3 + K_4)$$

where

$$\begin{aligned}K_1 &= f(x_n, y(x_n)) \\K_2 &= f\left(x_n + \frac{h}{2}, \eta_n + \frac{h}{2}K_1\right) \\K_3 &= f\left(x_n + \frac{h}{2}, \eta_n + \frac{h}{2}K_2\right) \\K_4 &= f(x_{n+1}, \eta_n + hK_3)\end{aligned}$$

- The resulting prescription of the Classical method:

$$\eta_{n+1} = \eta_n + \frac{h}{6}(K_1 + 2K_2 + 2K_3 + K_4). \quad (12)$$

## Application of Runge-Kutta method

- Let us denote:

$$\frac{\partial N(r, Y)}{\partial Y} = \int d\vec{r}_1 K(\vec{r}, \vec{r}_1, \vec{r}_2) (N(r_1, Y) + N(r_2, Y) - N(r, Y) - N(r_1, Y)N(r_2, Y))$$

$$N(r, Y = 0) \equiv N_0(r)$$

$$I(r) \equiv \int d\vec{r}_1 K(\vec{r}, \vec{r}_1, \vec{r}_2) (N(r_1, Y) + N(r_2, Y) - N(r, Y) - N(r_1, Y)N(r_2, Y))$$

$$f(r, r_1) \equiv K(r, r_1, r_2) (N(r_1, Y) + N(r_2, Y) - N(r, Y) - N(r_1, Y)N(r_2, Y))$$

- $r_2$  is obtained from  $r$  and  $r_1$
- Let's now apply the forward Euler method to the BK equation...

## Application of the Runge-Kutta methods

- At  $Y_0 = 0$  we define the values of  $r[n]$  and therefore we obtain  $N_0(r)$
- For each  $r$  we know  $r_1[n]$  and therefore we obtain  $N_0(r_1)$
- Using values of  $r[j]$  and  $r_1[j]$  we obtain the values of  $r_2$  and  $N_0(r_2)$  and  $K(r, r_1, r_2)$
- The integral is therefore  $I(r) = \int d\vec{r}_1 f(r, r_1)$
- Apply the Simpson's rule to the integral  $I(r)$
- The approximation of  $N$  at rapidity  $Y_1 = Y_0 + \Delta Y$  is then given as

$$N_1(r) = N_0(r) + \Delta Y I(r)$$

- The same procedure is applied at the next rapidity step
- The evolution of  $N(r, Y)$  is possible to any desired rapidity  $Y$
- For RK methods of higher order the evolution prescription is modified according to the given method

**Thank you for your attention**